

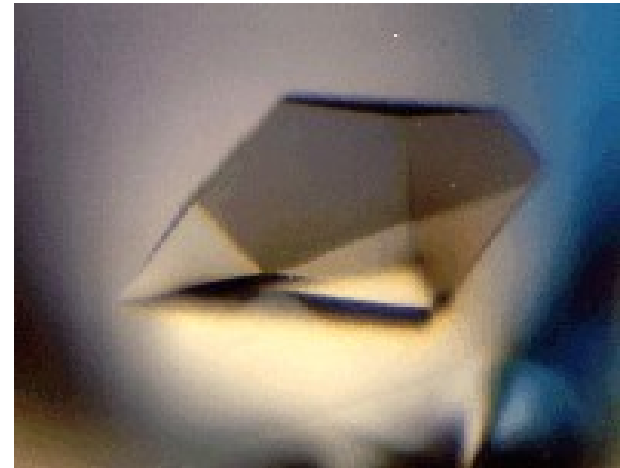
# Bioinformatics III

## Analysis and prediction of 3D macromolecule structures

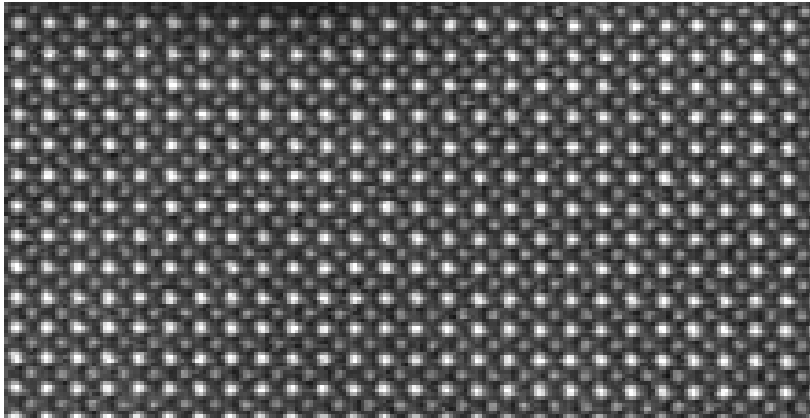
Lecture 8 – symmetry

Saulius Gražulis  
2022

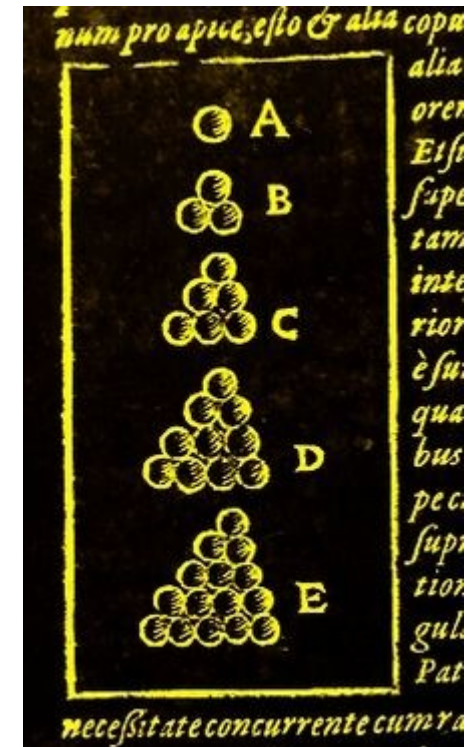
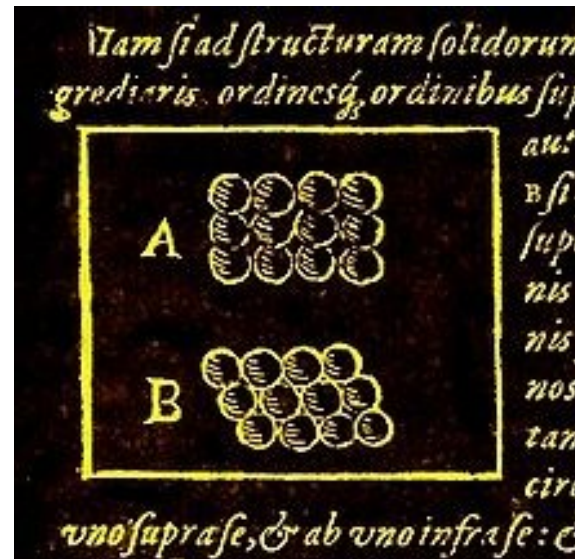
# Crystals



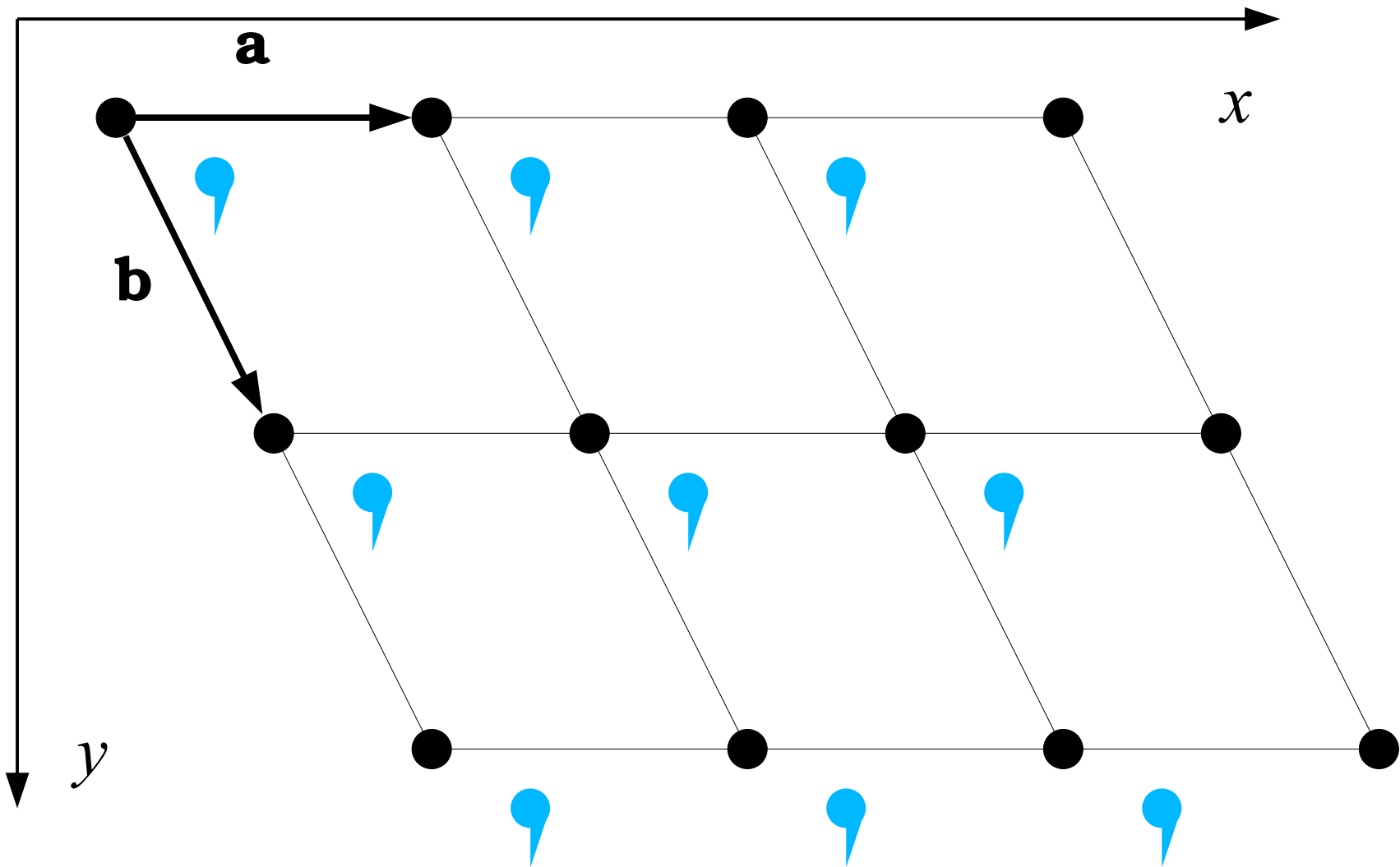
# Explanation of crystal shape



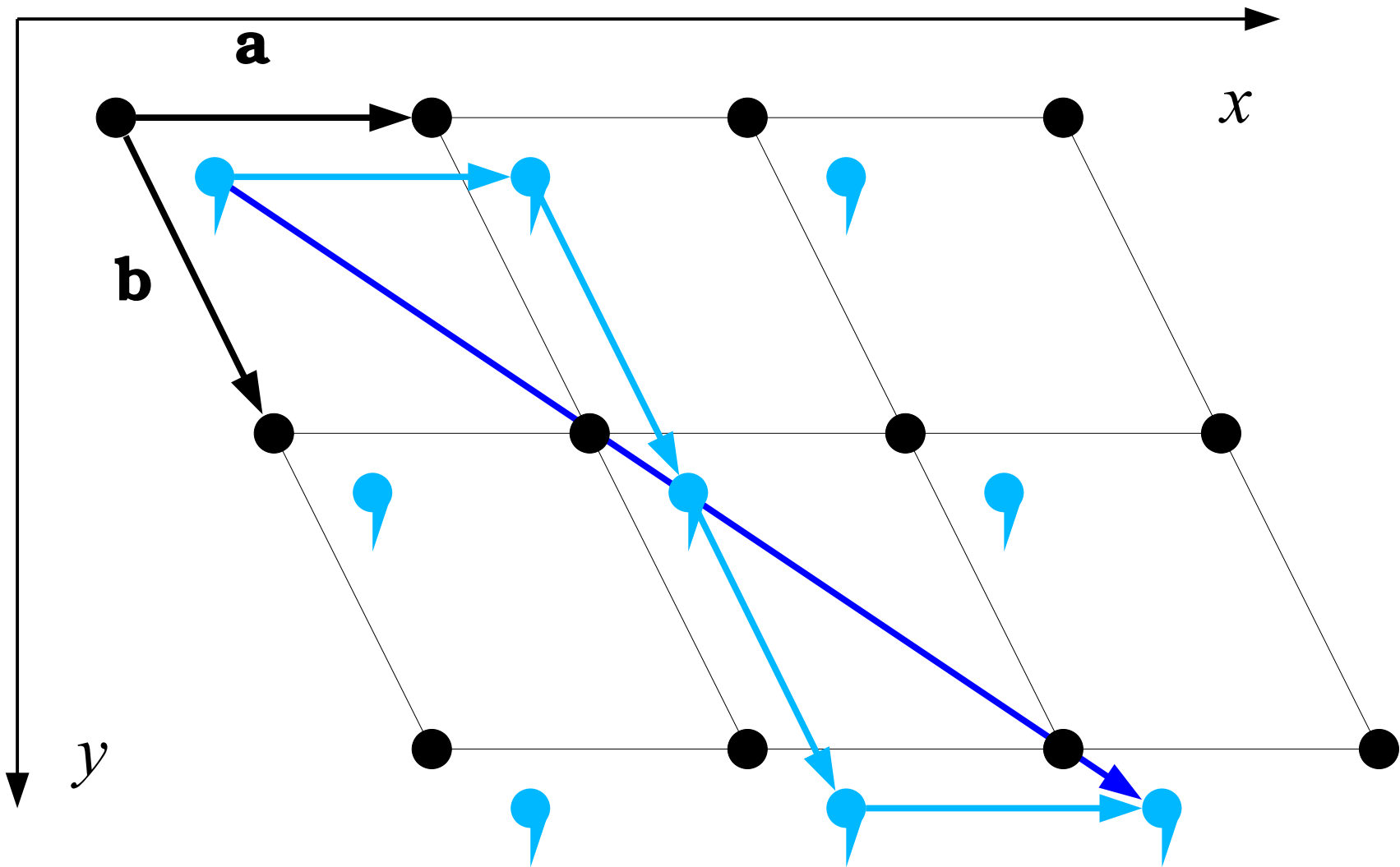
Johannes Kepler  
1611 m. „Strena Seu  
de Nive Sexangula“  
(A New Year's Gift of  
Hexagonal Snow)



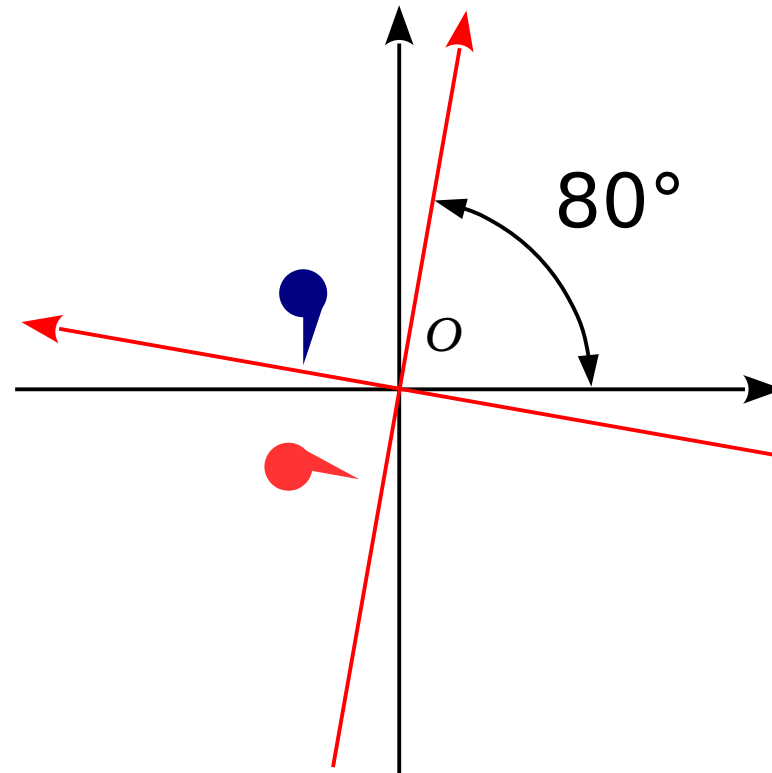
# Periodicity and translations



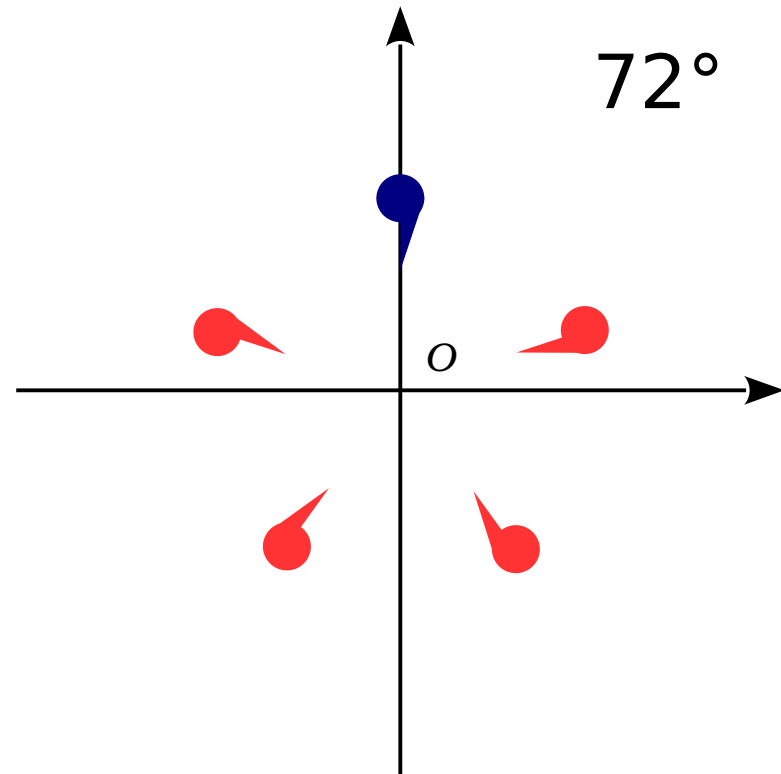
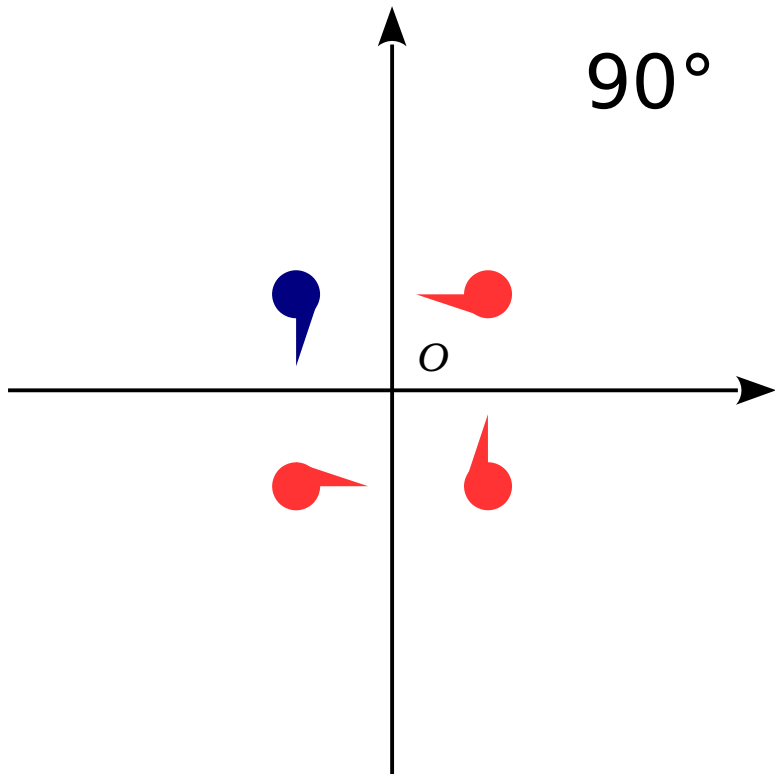
# The translation group



# Point symmetry elements



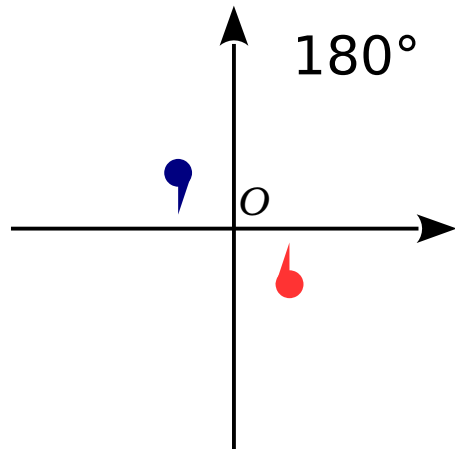
# Point groups



# Description of symmetry

Coordinates of a general position:

$$-x, -y, z + \frac{1}{2}$$



Rotation matrix + translation

$$\vec{x}' = R \vec{x} + \vec{T}$$

$$\begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0.5 \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} r_{11} & r_{12} & r_{13} \\ r_{21} & r_{22} & r_{23} \\ r_{31} & r_{32} & r_{33} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} + \begin{bmatrix} t_x \\ t_y \\ t_z \end{bmatrix}$$

# Combination of symmetry elements

$$\vec{x}' = R\vec{x} + \vec{T}$$

$$\begin{aligned}\vec{x}'' &= R'(R\vec{x} + \vec{T}) + \vec{T}' = \\ &= R'R\vec{x} + R'\vec{T} + \vec{T}'\end{aligned}$$

$$S = R + \vec{T}; S' = R' + \vec{T}'$$

$$S'S = R'R + (R'\vec{T} + \vec{T}')$$

$$R'R = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$-x, -y, z$

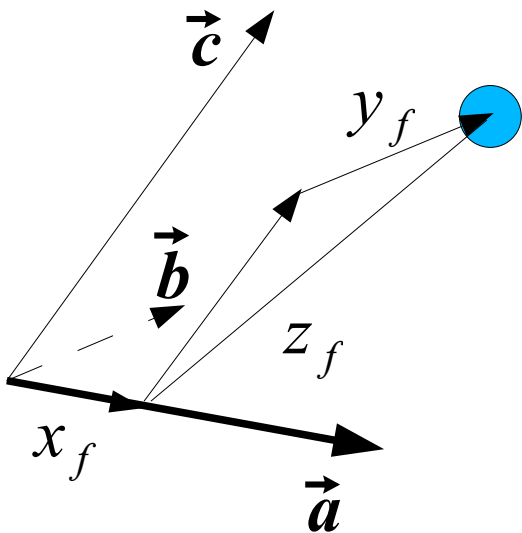
$-x, y, -z$

$x, -y, -z$

# Coordinates

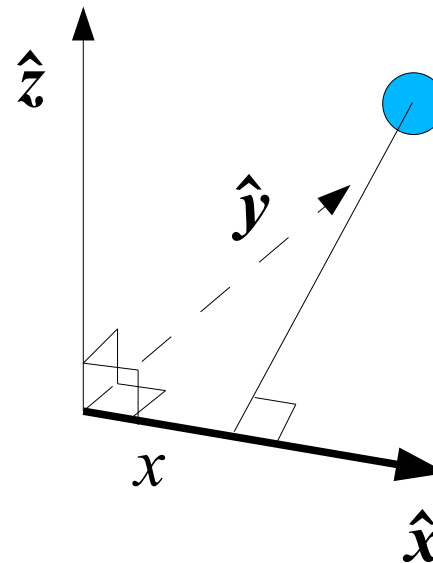
Fractional

(as fractions of unit cell vectors)



Cartesian  
(orthonormal)

In an orthonormal basis (coordinate system)



# Coordinate transformations (Perl)

$$\vec{x}' = R\vec{x} + \vec{T}_o$$

```
sub symop_ortho_from_fract
{
    my @cell = @_;
    my ($a, $b, $c) = @cell[0..2];
    my ($alpha, $beta, $gamma) = map { $Pi * $_ / 180 } @cell[3..5];
    my ($ca, $cb, $cg) = map { cos } ($alpha, $beta, $gamma);
    my $sg = sin($gamma);

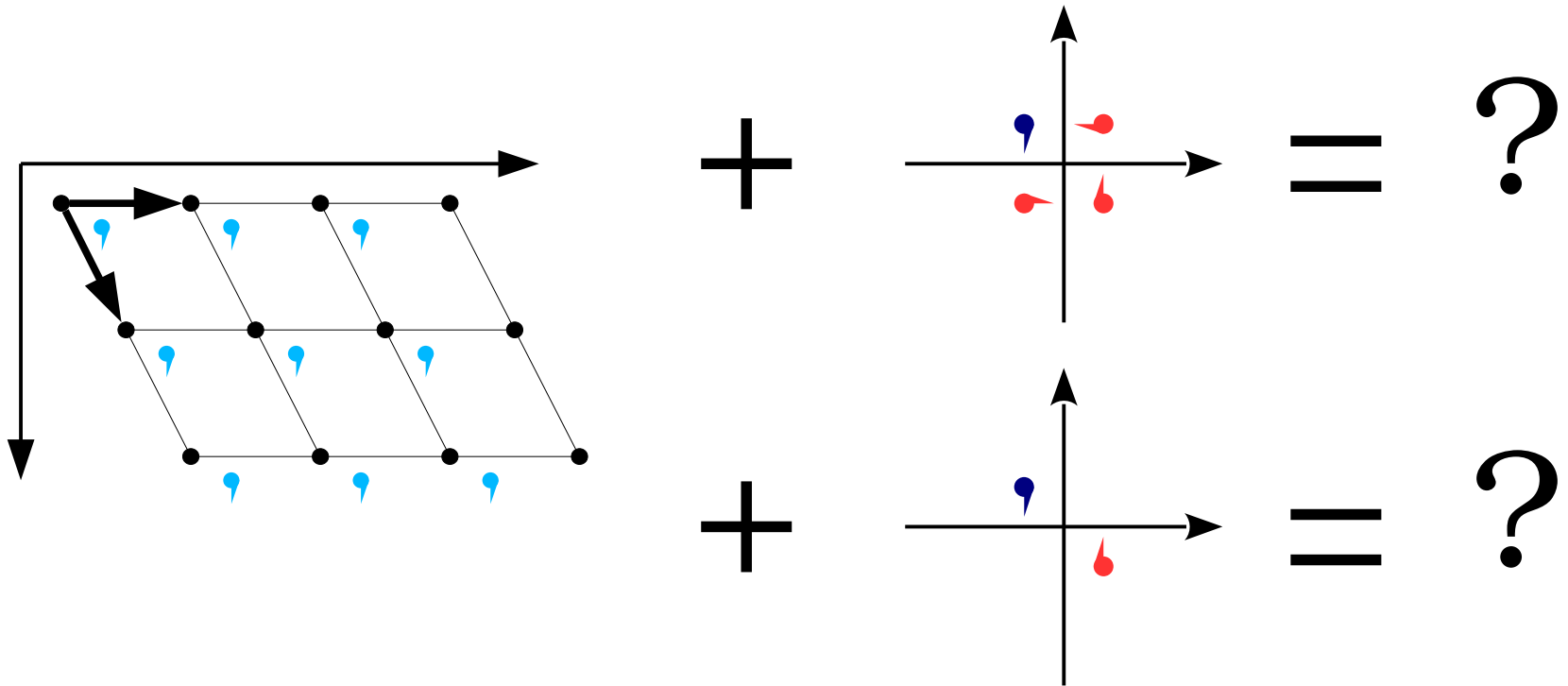
    return [
        [ $a, $b*$cg, $c*$cb ],
        [ 0, $b*$sg, $c*($ca-$cb*$cg)/$sg ],
        [ 0, 0,
          $c*sqrt($sg*$sg-$ca*$ca-$cb*$cb+2*$ca*$cb*$cg)/$sg ]
    ];
}
```

# Coordinate transformations (Ada)

$$\vec{x}' = R \vec{x} + \vec{T}_o$$

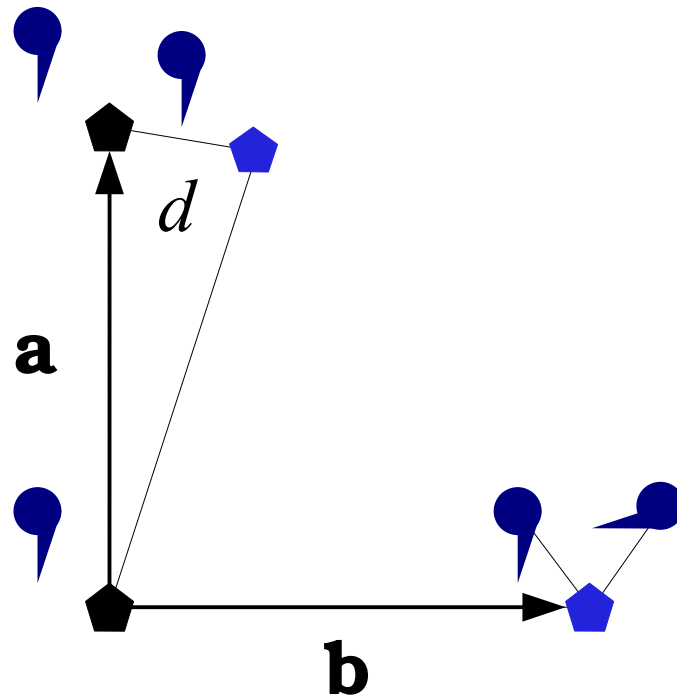
```
function Matrix_Ortho_From_Fract ( Cell : Unit_Cell_Type )
    return Matrix3x3
is
    A : Long_Float := Cell(1);
    B : Long_Float := Cell(2);
    C : Long_Float := Cell(3);
    Alpha : Long_Float := Cell(4) * Ada.Numerics.Pi / 180.0; -- in radians;
    Beta : Long_Float := Cell(5) * Ada.Numerics.Pi / 180.0;
    Gamma : Long_Float := Cell(6) * Ada.Numerics.Pi / 180.0;
    CA : Long_Float := Cos(Alpha);
    CB : Long_Float := Cos(Beta);
    CG : Long_Float := Cos(Gamma);
    SG : Long_Float := Sin(Gamma);
begin
    return (
        ( A, B * CG, C * CB ),
        ( 0.0, B * SG, C * (CA - CB*CG) / SG ),
        ( 0.0, 0.0,
          C * Sqrt (SG*SG - CA*CA - CB*CB + 2.0*CA*CB*CG)/SG )
    );
end;
```

# Translations with point groups = space groups



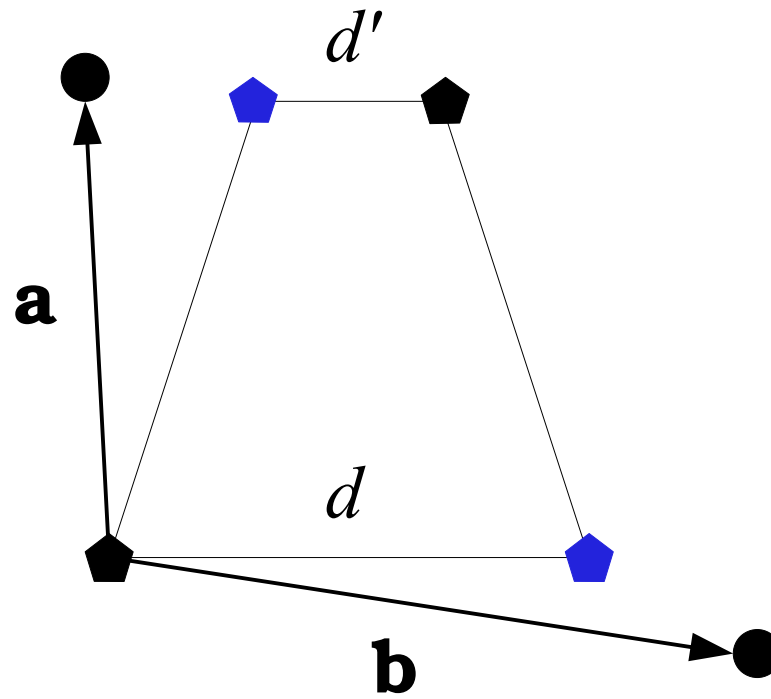
# Symmetry elements compatible with lattices

*Why don't you see five-sided snowflakes?*

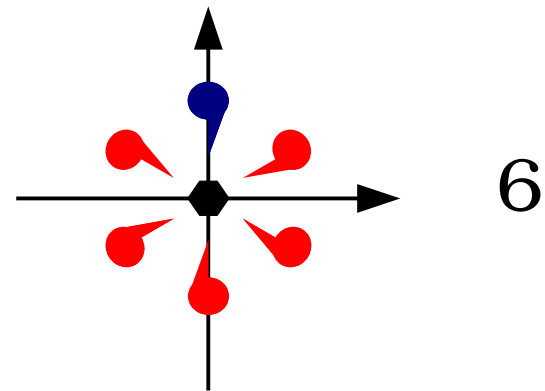
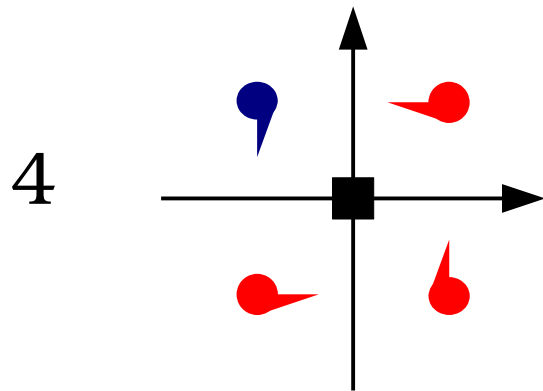
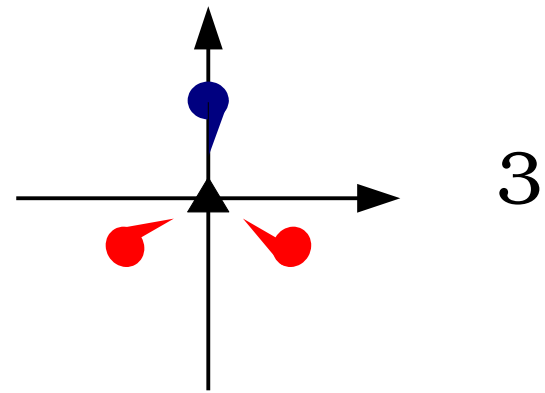
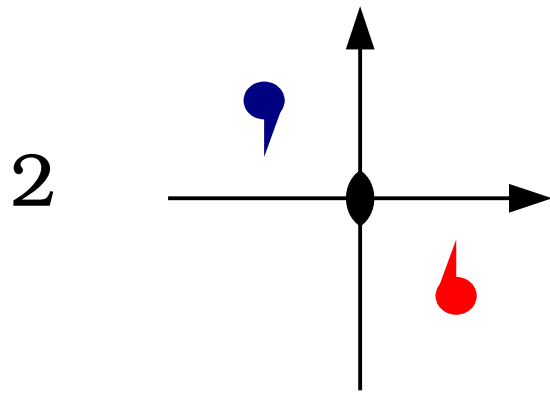


# Symmetry elements compatible with lattices

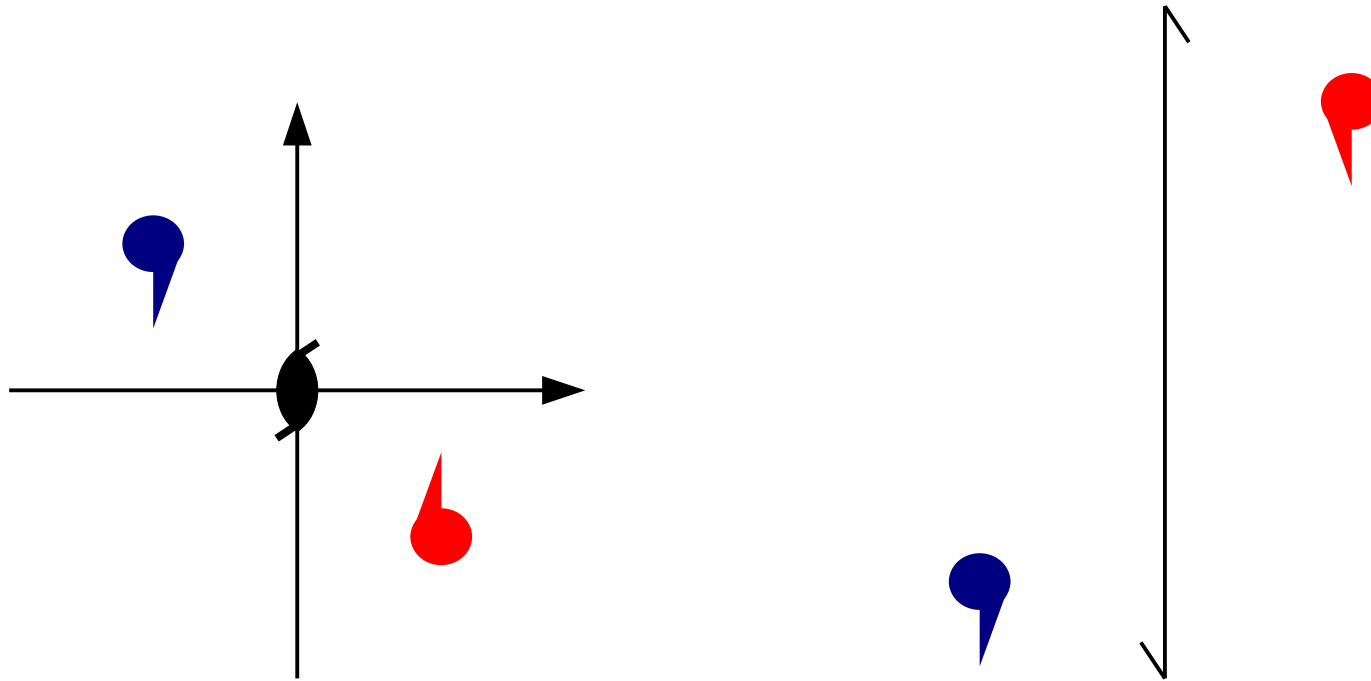
*Why don't you see five-sided snowflakes?*



# Symmetry elements: rotation axes



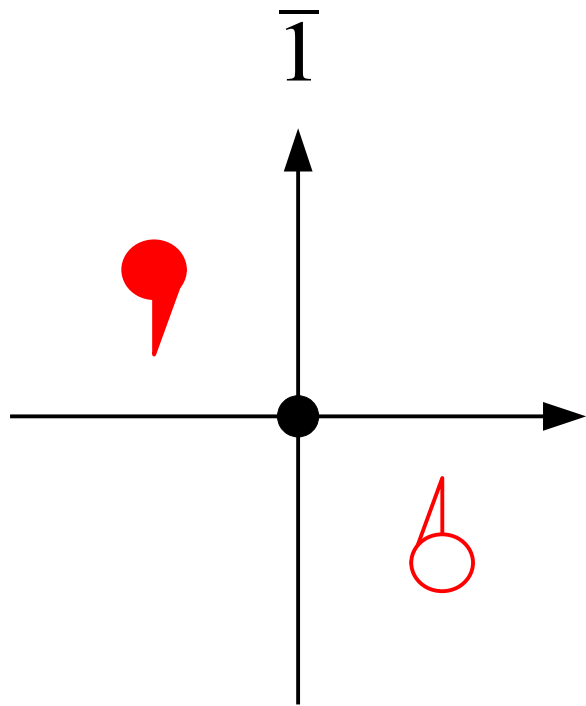
# Symmetry elements: screw axes



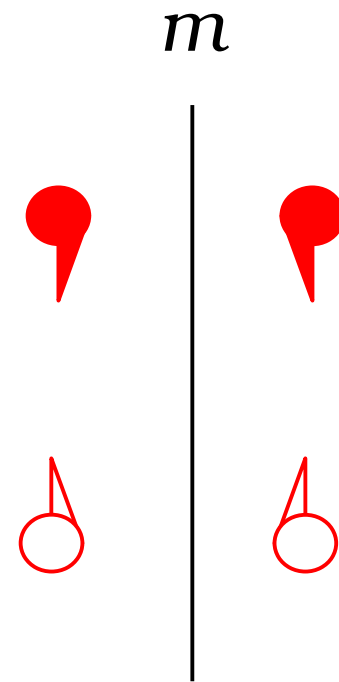
Sraigtinės ašys:  $2_1$

Kitos galimybės:  $3_1$ ,  $3_2$ ,  $4_1$ ,  $4_2$ ,  $4_3$ ,  $6_1$ ,  $6_2$ ,  $6_3$ ,  $6_4$ ,  $6_5$

# Inversion centres and mirror planes

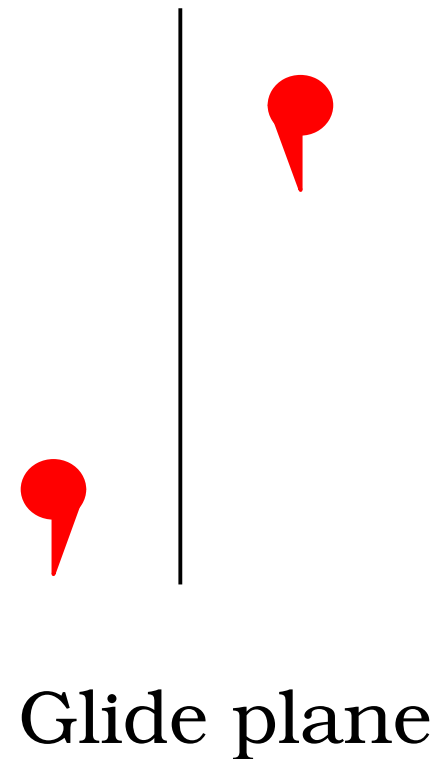
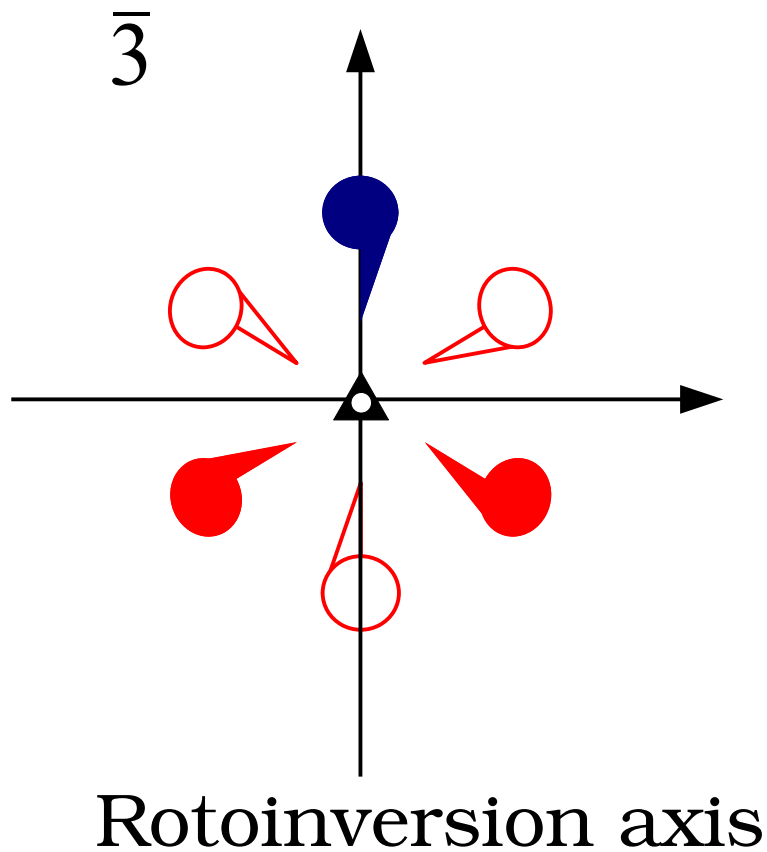


Inversion centre



Mirror plane

# Rotoinversion axes; glide planes



# Nomenclature of space groups

Hermann–Mauguin symbols

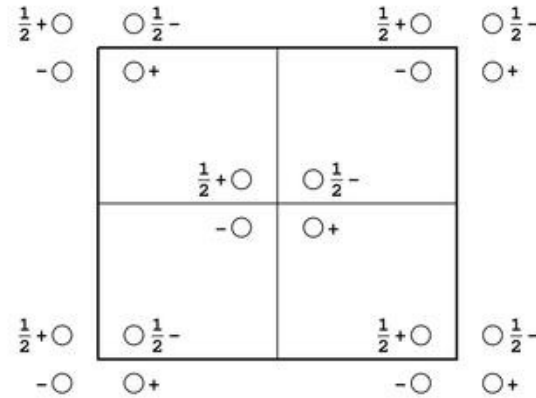
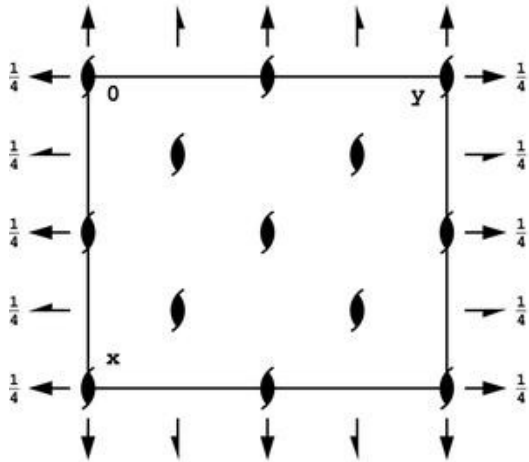
e.g.:  $P2_12_12_1$     $C2$     $F432$

- 230 space groups
- 65 Sohncke groups (preserve chirality; available for biomolecules ;)

Other nomenclatures:  
Schönflies symbols, Hall symbols

# International Tables for Crystallography

$C222_1$



- (1)  $x, y, z$       (2)  $\bar{x}, \bar{y}, z + \frac{1}{2}$       (3)  $\bar{x}, y, \bar{z} + \frac{1}{2}$       (4)  $x, \bar{y}, \bar{z}$   
 (5)  $x + \frac{1}{2}, y + \frac{1}{2}, z$       (6)  $\bar{x} + \frac{1}{2}, \bar{y} + \frac{1}{2}, z + \frac{1}{2}$       (7)  $\bar{x} + \frac{1}{2}, y + \frac{1}{2}, \bar{z} + \frac{1}{2}$       (8)  $x + \frac{1}{2}, \bar{y} + \frac{1}{2}, \bar{z}$

Space group  $C222_1$ :

Multiplicity,  
Wyckoff letter,  
Site symmetry

Coordinates

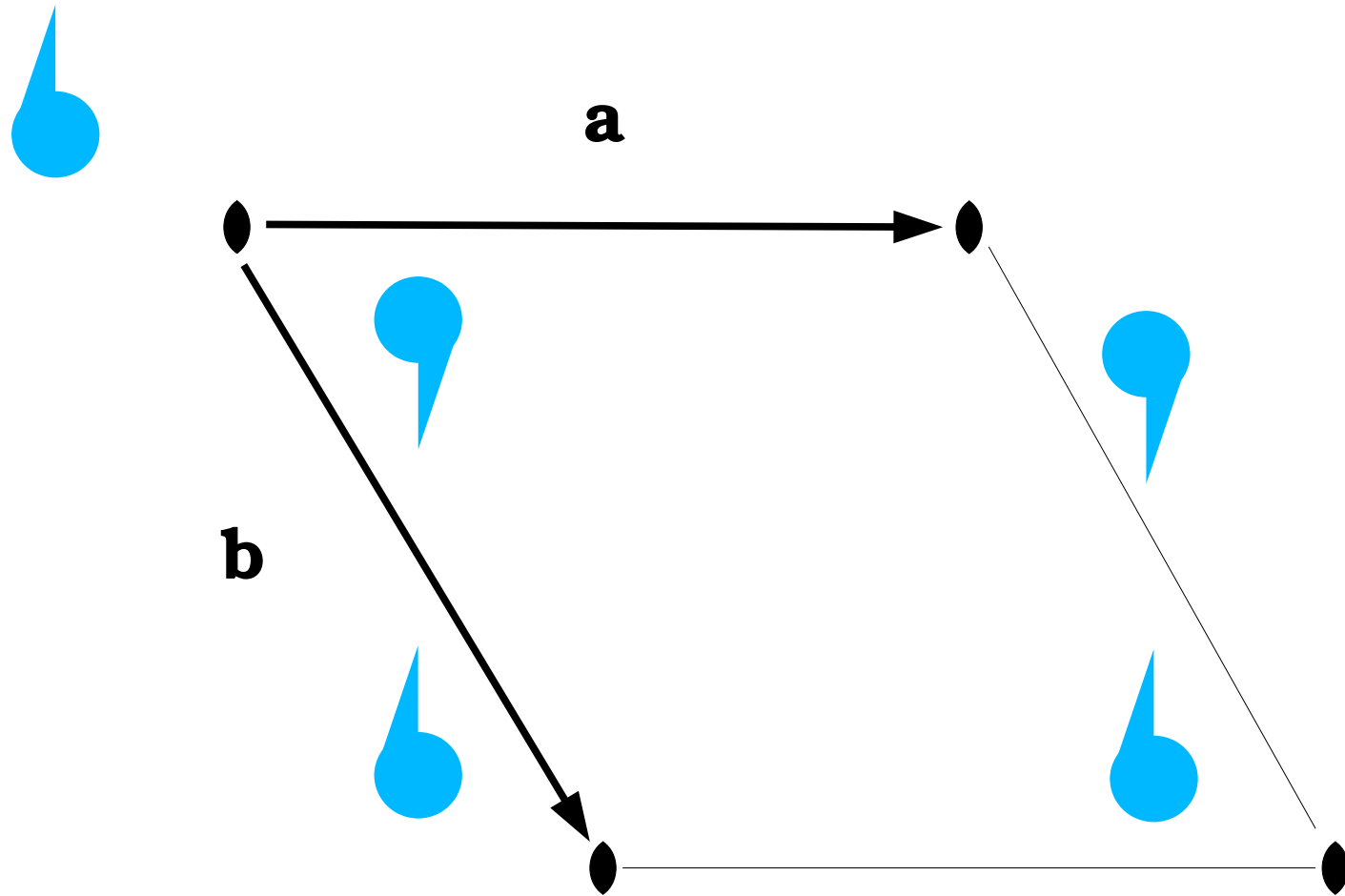
Multiplicity, Wyckoff letter, Site symmetry	Coordinates
8 <i>c</i> 1	(1) $x, y, z$ (2) $\bar{x}, \bar{y}, z + \frac{1}{2}$ (3) $\bar{x}, y, \bar{z} + \frac{1}{2}$ (4) $x, \bar{y}, \bar{z}$
4 <i>b</i> .2.	$0, y, \frac{1}{4}$ $0, \bar{y}, \frac{3}{4}$
4 <i>a</i> 2..	$x, 0, 0$ $\bar{x}, 0, \frac{1}{2}$

Zbigniew Dauter; Mariusz Jaskolski *How to read (and understand) Volume A of International Tables for Crystallography...*, JAC 43(5) 2010

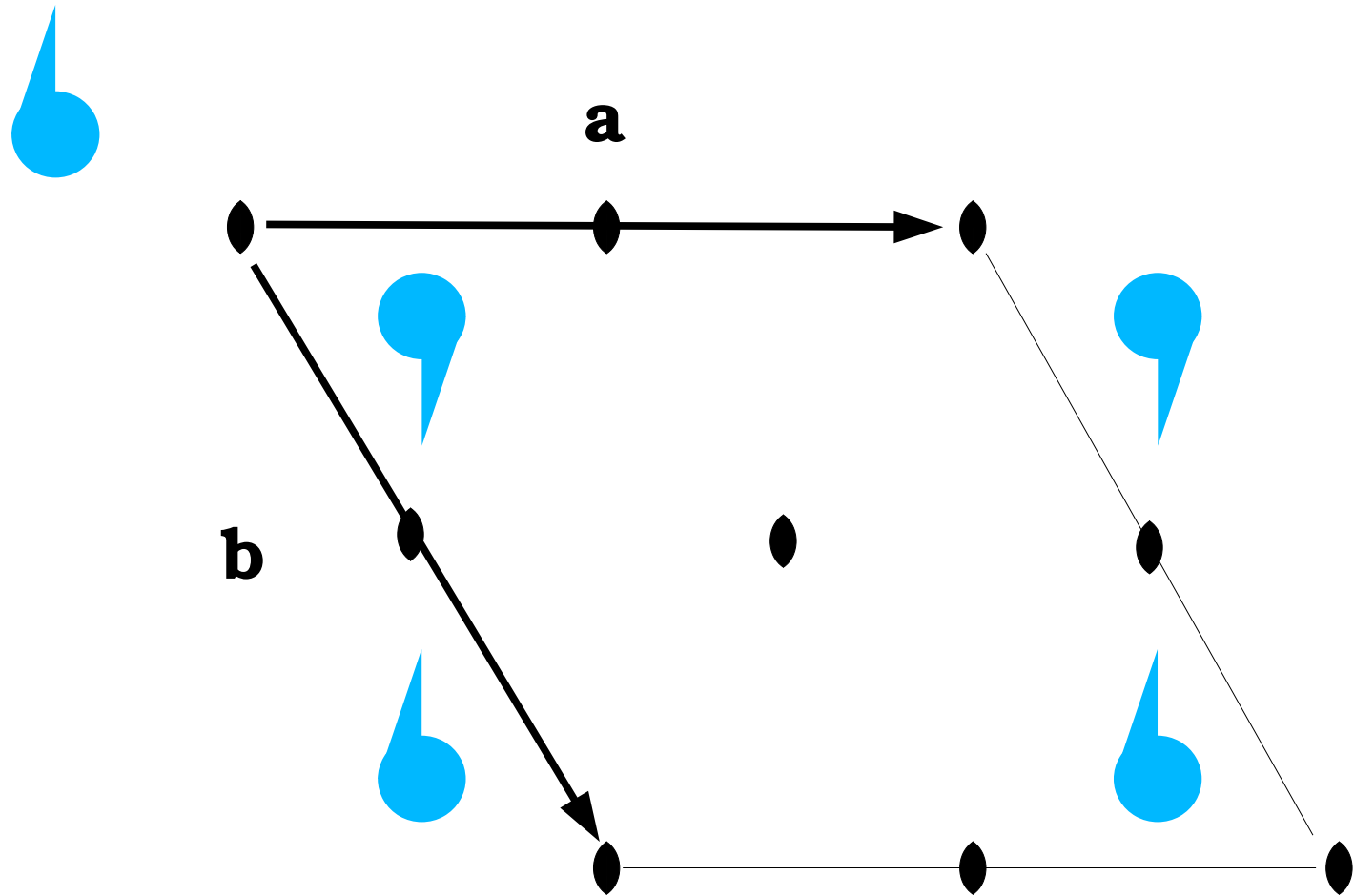
<http://journals.iucr.org/j/issues/2010/05/02/kk5061/index.html>

<http://journals.iucr.org/j/issues/2010/05/02/isscontsbdy.html>

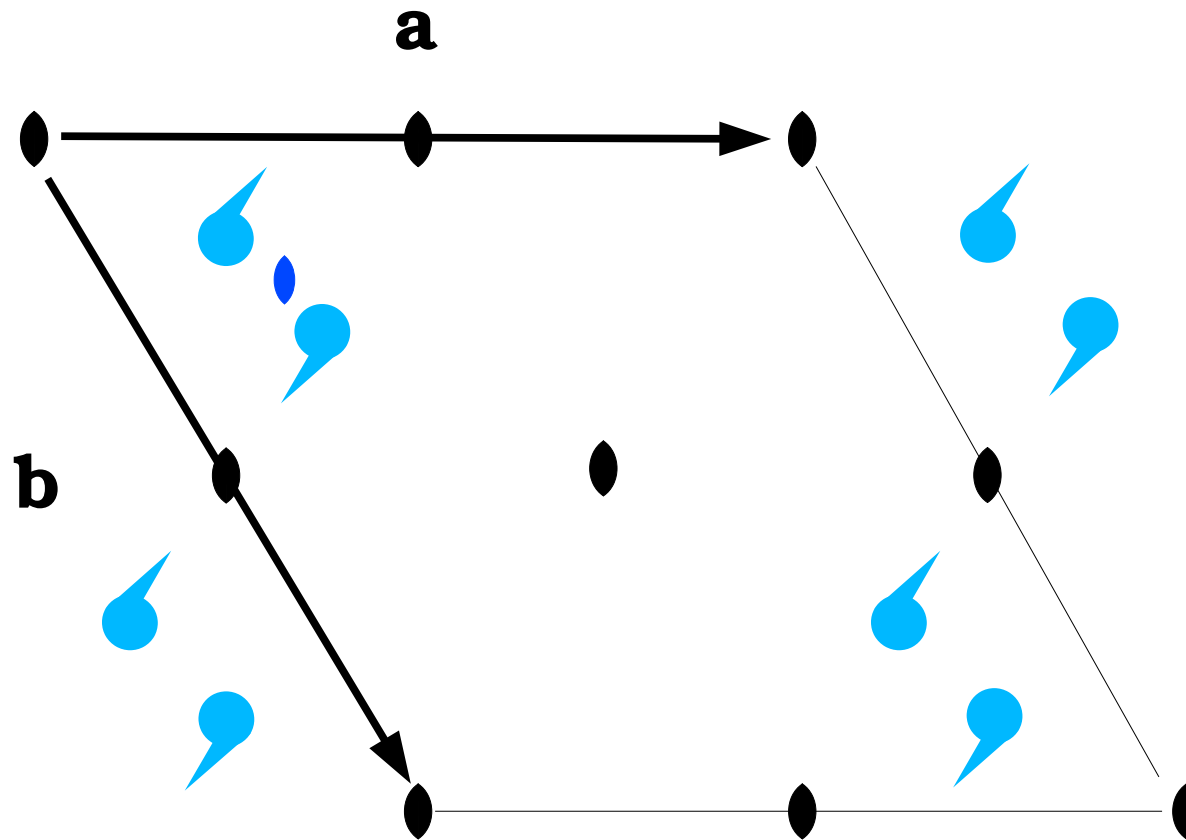
# Filling the lattice



# Asymmetric unit



# Non-crystallographic symmetry



# Relation of asymmetric and biological unit

- Asymmetric unit contains one or several protein/NA chains
- Biological unit can have various relations to the asymmetric unit ( $1/2$ ,  $2$ ,  $1\ 1/2$ , and so forth)